

METHOD FOR CONTROLLING POWER FLOWS

The invention relates to a method for controlling energy sources or energy sinks on an energy accumulator, in particular
5 in a motor vehicle.

The subject matter of the invention relates mainly to the field
of automobile engineering in which case, in consequence, the
expressions energy accumulator and battery or vehicle battery
10 are used synonymously.

Electrical couplings or clutches, electrically operated lifting
ramps, winch motors, drive-by-wire controllers, steer-by-wire
controllers, electrical retarder supports, automotive image
15 identification systems, radar-sensor systems, information
system modules for organization of the unloading and loading of
commercial vehicle cargoes on fleet parking areas and various
further electrically operated systems assist the driver to
carry out his tasks. The large number of these electronic
20 information, control and loading systems, the increasing
electrification of previously mechanical driving aids and
equipment, and the increasing level of motorization with
correspondingly larger starting aids require a large amount of
electrical energy, and thus have a direct influence on the life
25 of vehicle batteries. In consequence, any shortage in the
battery-fed energy supply in vehicles such as these also
results in a drastic increase in the risk of breakdown.
Vehicles with a high risk of breakdown, in particular
commercial vehicles, do not comply with the requirements for a
30 high degree of mobility, and can be used only to a restricted
extent.

Various apparatuses and methods for optimization of the state
of charge and thus also of the life of vehicle batteries are
35 already known, and are currently used in particular cases in

passenger vehicles. By way of example, batteries are equipped with sensors and actuators which readjust their own temperature when cold. In consequence, the chemical reaction rates are increased, and the battery can be recharged within a shorter 5 time. So-called integrated battery diagnosis systems are also known, which are integrated directly in the battery as a small electronic assembly, and lengthen the life of the battery.

However, none of the abovementioned systems overcomes the 10 reason for restrictions to the availability of energy accumulators and the high costs associated with them as a result of their failures.

In this context, the invention is based on the object of 15 specifying a method of the type mentioned initially, which ensures that an energy accumulator, in particular a vehicle battery, is operated in as optimum a fail-safe manner as possible. An apparatus for carrying out the method is also the subject matter of the invention.

According to the invention, the object is achieved by means of 20 the subject matter of the first claim and of claim 9. The respective dependent claims describe advantageous refinements and developments of the solution found.

The state of charge of the battery depends not only on the 25 battery characteristic data but also on a large number of further factors. In addition to the battery characteristic variables, the acid levels of the battery, the load power 30 levels, the charging voltage, the dynamic system characteristics and the nature of the vehicle use also govern the life of the battery, and hence also the risk of the vehicle breaking down.

The central element that is currently implemented in all vehicles for detection of a large number of parameters which are relevant for the state of charge of the battery, such as the vehicle power supply system voltage, the rotation speed, 5 the speed, the temperatures, etc., and for controlling a large number of electrical loads, is the instrumentation unit, in this case referred to for short as the combination instrument. The information flow which coincides here, combined with the capability to control parameters relating to the system- 10 internal power flows, is particularly suitable for integration of the method described in this invention. The present trend for modularization of individual system components in the vehicle and for connection to universal networks, such as CAN, RS485, LON or K-line, is opening up the option not only of 15 further concentration of functionality in the combination instrument, but also of centrally influencing virtually all system components and loads in the vehicle. In addition, connections which are not cable-based, such as Bluetooth, also according to the invention allow the control of components 20 which are not wired in as standard, for example retrofitted components. The central implementation of functionalities in a control unit makes it possible to avoid some of the sensitive electronics, thus improving the reliability and lengthening the life of the overall system.

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A further advantage of the invention is the use of criteria which allow adaptation of the method and of its implemented routines to different energy sinks and energy sources, such as different battery types, thus making it possible to ensure use 30 that is as versatile as possible. In addition to automatic control by the system, active, assessing, manual action on the overall system is also possible, thus allowing adaptations to be carried out for different situations and characteristics relevant to the vehicle and the journey profile.

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One advantageous development of the invention advantageously uses apparatuses and methods for evaluation and control of driver-relevant, transport-logistic or vehicle-relevant data, with the apparatuses or methods that can be used being, for
5 example, so-called generator regulators, electronic battery heating management systems, temperature sensors for the battery and the engine bay, acid density meters for batteries, sensors and actuators for energy sources and energy sinks, route planners, detectors for detection of system characteristics,
10 systems for controlling ignition and injection systems (engine control), and systems for controlling logistic processes for passenger vehicle and commercial vehicle traffic.

In order to provide further illustration, the most important of
15 the apparatuses and methods mentioned above will be explained or defined briefly in the following text.

Generator regulators compensate for the voltage differences caused by rotation speed and load fluctuations.

20 Battery heating management systems use a measurement and control unit which is located in the battery housing to determine the temperature of the battery, and to readjust it.

25 Acid density meters for batteries determine the acid density and acid stratification of the batteries.

Acid regulators compensate for chemically non-uniform states.

30 Load meters and load controllers for loads in the vehicle determine and control the energy and time profile of continuous loads, long-term loads and short-term loads.

35 Detectors on the battery detect the interaction of battery, generator, loads, temperature, rotation speed and transmission

ratio from the engine to the generator, and transmit a characteristic which describes this system.

5 Systems for controlling the ignition and injection system or engine management systems, such as motronic systems, detect and control instantaneous engine operating data and communicate with other vehicle controllers.

10 Systems for controlling individual goods vehicles and goods vehicle fleets, so-called wap-log systems, analyze the processes relating to transport logistics. The company procedures with generally different types of traffic are stored in a database. Depending on the specific application, a relevant model is activated, in which details of the task 15 processes and of the present order are recorded, so that the driver is guided through his journey profile by mobile radio step-by-step by means of an information system which is based on a wireless application protocol, referred to for short as WAP, on the general packet radio service, referred to as GPRS 20 for short.

The battery temperature at which the engine can still be started depends on the minimum state of charge of the battery.

25 The current emitted from the generator is dependent on the rotation speed. If the load current is greater than the generator current, for example when the engine is idling, the battery is discharged, and the voltage in the vehicle power supply system falls.

30 The rotation speed which is offered to the generator depends on the use of the vehicle, such as commercial traffic, driving on freeways, driving in towns, etc.

The load power levels are governed by the electrical loads. In a vehicle, these comprise permanent loads (ignition, fuel injection, etc.), long-term loads (lighting, brake light, etc.) and short-term loads (blinkers, brake light, etc.), and they are switched on for different periods. In some cases, they are dependent on the time of year (air-conditioning system, seat heating) or are dependent on the type of driving (cooling fans).

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10 The charging voltage has to vary depending on the chemical processes in the battery. Cold requires a high charging voltage, while heat requires a lower charging voltage.

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The interaction of the battery, generator, loads, temperature, rotation speed and transmission ratio from the engine to the generator is described by the system characteristic. This changes dynamically depending on the vehicle operating condition.

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25 The battery acid levels determine the density of the electrolyte, which is provided as the ion conductor between the pole plates, varying with the charging voltage, and can be used as a measure for this. Typical values between a charged battery and a discharged battery fluctuate in the case of low-acid rechargeable batteries ($PbO_2-H_2So_4-Pb$) between 1.28 kg/l and 1.04 kg/l.

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35 The maximum power of the generator rises with the rotation speed. In the case of modern vehicles, engine idling represents about one-third of the rotation speed probabilities of the generator. The power emitted from the generator is controlled by means of the field current. The current output function has a curved profile when plotted against the rotation speed. This so-called maximum current characteristic rises from the 0-ampere rotation speed up to the idling rotation speed, but then

rises only slightly up to the maximum rotation speed, in order to ensure overload protection.

The systems are controlled by means of a generator regulator,
5 specifically a standard regulator or multifunction regulator. Standard regulators normally have a temperature-dependent preset nominal value, which is higher when it is cold in order to improve battery recharging, which is then more difficult. Modern multifunction regulators have an interface which, within
10 certain limits, allows fine tuning with respect to the engine operating state.

Engine management systems are systems for controlling the ignition and injection system, such as motronic systems, and
15 carry out the detection and control of instantaneous engine operating data, on a microprocessor-controlled basis. They communicate with other vehicle controllers via the CAN bus system. Typical engine operating data includes the accelerator pedal position, the ignition data, the air flows, the rotation
20 speed, the temperatures, the battery voltage, the fuel flow, the speed of travel, the torque, the mixture ratio, the exhaust gas data, etc.

The method according to the invention can advantageously
25 provide for prioritization, filtering and normalization of various data formats to be carried out with the aid of a data mask. This means that the actual core algorithm for generation of control signals for power loads or power feeders remains free of module-specific data format corrections, and is thus
30 clear.

One embodiment of the method according to the invention is particularly expedient when the future time profile of the state of charge of the energy accumulator is signaled to a
35 user, in particular being indicated on a display or signaled

acoustically. The vehicle driver of the motor vehicle therefore does not have to blindly trust a system with the method according to the invention and can always reassure himself that the procedure proposed by the method is worthwhile.

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The control unit which generates control signals can expediently be connected to actuators by means of which engine parameters can be adapted. By way of example, a controller for an automatic transmission can be matched with respect to the 10 rotation speed behavior on load in such a way that the drive rotation speed for the generator is increased when required. In addition, however, it is also expedient to connect actuators to the control unit which control high-load infotainment elements 15 on a state of charge-dependent basis, for example switching them off when the state of charge is critical. The method according to the invention is additionally optimized if the control unit is able to calculate the energy consumption of energy sinks on the planned route in advance, for example by using data from a navigation system and vehicle-specific 20 characteristic data to produce an appropriate prediction.

It is particularly expedient for the control unit according to the invention to be integrated as a component in a combination instrument. Combination instruments are already a destination 25 point for all the information flows from the motor vehicle system.

One preferred variant of the solution found provides for logic linking and assessment of some of the data obtained by means of 30 the abovementioned apparatuses and methods to be carried out in the combination instrument such that either optionally or automatically on a predetermined basis an energy situation is recommended which has been optimized for the overall system comprising the vehicle, the roadway and the route, or a

situation is forced that offers an optimized charging state and final charge state for the energy accumulator or the battery.

The method is advantageously implemented by means of an apparatus according to the invention, which expediently has a control unit that is included in a combination instrument, with the control unit having a remote data transmission module, an engine management module, a battery management module, a temperature module, a data input module, a filter, a memory, a logic module, a wire-free load controller or a wire-based load controller.

The invention will be explained in more detail in the following text on the basis of one specific exemplary embodiment and with reference to a drawing for illustrative purposes, without any restriction to this example. In the figure:

Figure 1: shows a system sketch of an apparatus which operates using the method according to the invention.

Figure 1 illustrates the data flows of input and output parameters 1 to 8, with the input and output parameters 1 to 6 being explained in detail in the following text, and the input and output parameters 7 to 8 being described as being representative of further channels which may possibly not always be used.

Essentially, a control unit 10 according to the invention for controlling energy sources 21 or energy sinks 22 on an energy accumulator 23 comprises input and output modules 1 to 8, a filter 9 for matching, standardization and normalization of data formats from or for the input and output modules 1 to 8, a logic module 12, a memory 11, a wire-free load controller 13 and a wire-based load controller 14. All of the abovementioned modules 1 to 14 have a connection which can carry a

bidirectional data flow to the connected adjacent module, with the input and output modules 1 to 8 each being connected to the filter 9, with the filter 9 being connected to the memory 11 and to the logic module 12, and with the logic module 12 having
5 a corresponding link to the load controllers 13, 14. The bidirectional data flow is illustrated in Figure 1 by means of a double-headed arrow which has a centrally arranged circle symbol. A unidirectional call to a module by means of a module connected adjacent to it is in each case symbolized by a single
10 arrow, as well. The input and output modules 1 to 8 call the filter 9, via a bus that is not illustrated, when data or measurement data is present. The filter 9 starts a call or is called by the modules, the logic module 12 and the memory 11. The logic module 12 calls the load controllers 13 or 14 as
15 required.

The energy accumulator 1 is in the form of a passive energy source, specifically a battery. The data to be transmitted to the filter 9 is information from a battery management system,
20 temperatures of the battery and chemical data.

The energy source 2 or the generator 21 which is illustrated in Figure 1, once again for simplicity purposes, in the connection of the generator 21, energy accumulator 23 and load 22,
25 comprises all of the active energy sources, specifically generators, generator regulators, solar collectors or external electrical power supplies connected to the vehicle.

Data is transmitted from a remote data transmitter 3 to the filter 9 and is used in the method for determination and for adjustment of a driving situation or route which is advantageous for charging and discharging of the battery. The state of charge and the charging time predictions are transmitted to a wap-log system, which transmits an optimized
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route back to the system according to the invention, on the basis of this data.

An engine management module 4 transmits parameters relating to
5 the ignition system and to the injection system to the filter
9, in particular engine temperatures and the rotation speed.
The system uses this data to identify whether the driver or the
vehicle controller should initiate a higher rotation speed in
order that the generator 21 will produce a higher charging
10 current.

A battery management module 5 supplies the filter 9 with
information relating to the electronic battery management, in
particular heat management. This essentially comprises the
15 temperature data for the energy accumulator 1, with an
operating temperature that is advantageous for the energy
accumulator 1 being produced.

A temperature module 6 supplies the control unit 10 according
20 to the invention, via the filter 9, with data relating to the
temperatures in the engine bay, temperatures relating to the
engine, and external ambient temperatures.

The filter 9 comprises a data mask which prioritizes the data
25 from the modules 1 to 8, adapting and filtering it with respect
to the data format. In addition, information is assessed and
weighted in advance in the filter 9 relating to its importance
for the driver, for the roadway, for the vehicle, for the
energy sources and for the energy sinks, in order to achieve a
30 processing time in the logic module 12 that is as short as
possible.

Data to be buffer-stored is stored temporarily or permanently
in a memory 11, so that it is available at short notice to the
35 program when required.

The information relating to the data mask, with prioritization and filtering 9, and the data from the memory 11 are logically linked and calculated in the logic module 12, so that the
5 results can then be processed further and preprocessed in the module for prioritization and filtering 9.

In the further method procedure, the individual control and measurement units described above, such as a generator regulator, electronic battery heat management systems, temperature sensors for the battery and the engine bay, acid density meters for batteries, sensors and actuators for energy sources and energy sinks, route planners, detectors for detection of system characteristics, systems for controlling the ignition and injection system, and systems for controlling logistic procedures in passenger vehicle and commercial vehicle traffic are instructed via the input and output modules 1 to 6, so that they can then be subjected by means of automatic control or by the driver to manipulation, such as activation, reduction of the rotation speed, connection of a second starter battery, indication of a good route from the energy point of view, heating of the battery, connection or disconnection of further energy sources, dimming of the lighting, load-related control of intelligent headlights, partial disconnection of individual infotainment elements, etc. The module 13 is used to control energy sinks 22 or loads, which are not specified in any more detail, via a wire-free connection, by means of simple status information from the load and simple directives relating to the permissible energy consumption, that is optimum from the
30 energy point of view.

The module 14 controls energy sinks 22 or loads, which are not specified in any more detail, using wires, by the provision of digital on/off control signals.

The exemplary embodiment envisages manipulation of the load-related control of various energy sinks 22 or loads, as will be explained in more detail in the following text for "intelligent headlights". "Intelligent" headlights, which use the advanced 5 front-lighting system (which is currently in experimental use), are also able to supply power to the lamps, by means of a controller. This headlight is connected to the vehicle CAN bus. The intensity and direction of the beam from the front headlight can be controlled specifically by the use of lenses, 10 mirrors or a DMD (digital micromirror device). The power and beam control are controlled in such a way as to achieve an optimum state of charge. In order to avoid adverse effects on driving safety resulting from lack of lighting of the roadway, necessary restrictions can be implemented, for example by 15 reducing the maximum speed, by actions on the engine controller.